



# Embedded Software Quality Challenge

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# Embedded Software Quality Challenge

## Lines of Code



**The complexity is growing at an increasing pace**

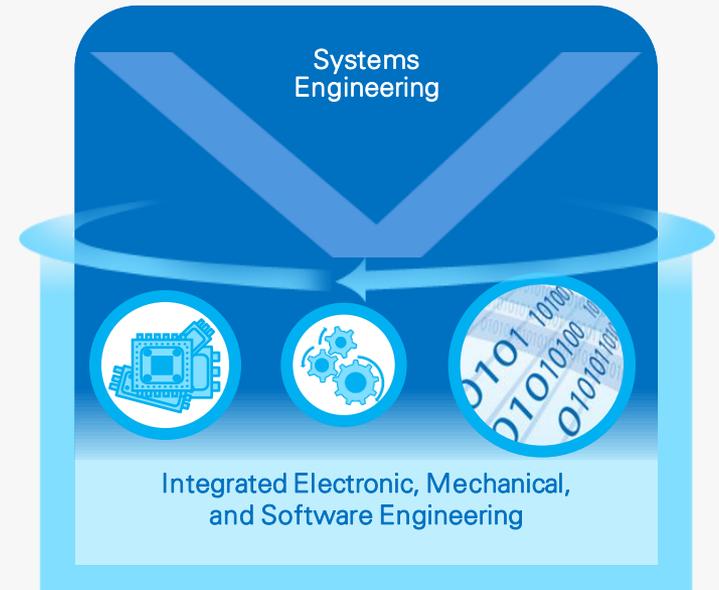
# Smarter Products Require New Technology

## Traditional Product & Systems Development



- Focused on CAD/CAM and BoM
- Slower to react to change
- Silos of engineering disciplines

## Next Generation Product & Systems Development



- More focus on software and electronics
- Responsive to change
- Systems engineering methods optimize product designs and engineering collaboration

# Managing the Cost of Software Errors

## Smart Washing Machine



## Commercial Aircraft



## Luxury Automobile



Lines of Code

100k

6.5 Mil

10 Mil

10-20 defects produced per 1,000 lines of code\*

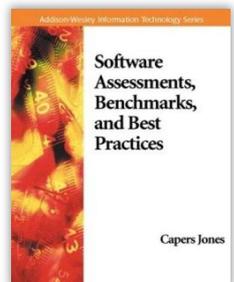
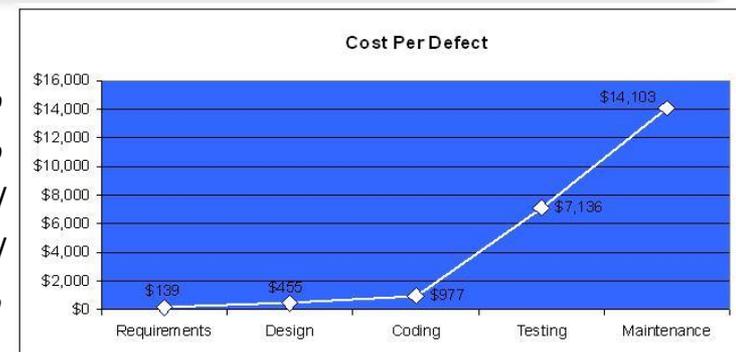
Defects

1k - 2k

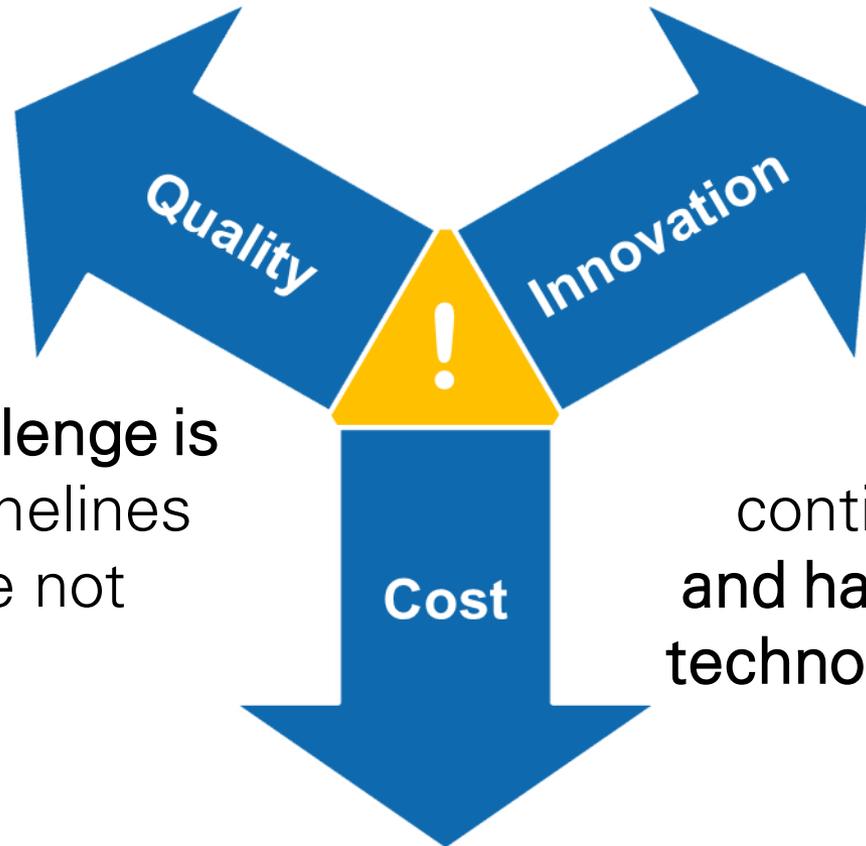
65k - 130k

100k - 200k

*...a bug which costs \$1 to fix on the programmer's desktop costs \$100 to fix once it is incorporated into a complete program, and many thousands of dollars if it is identified only after the software has been deployed in the field.*



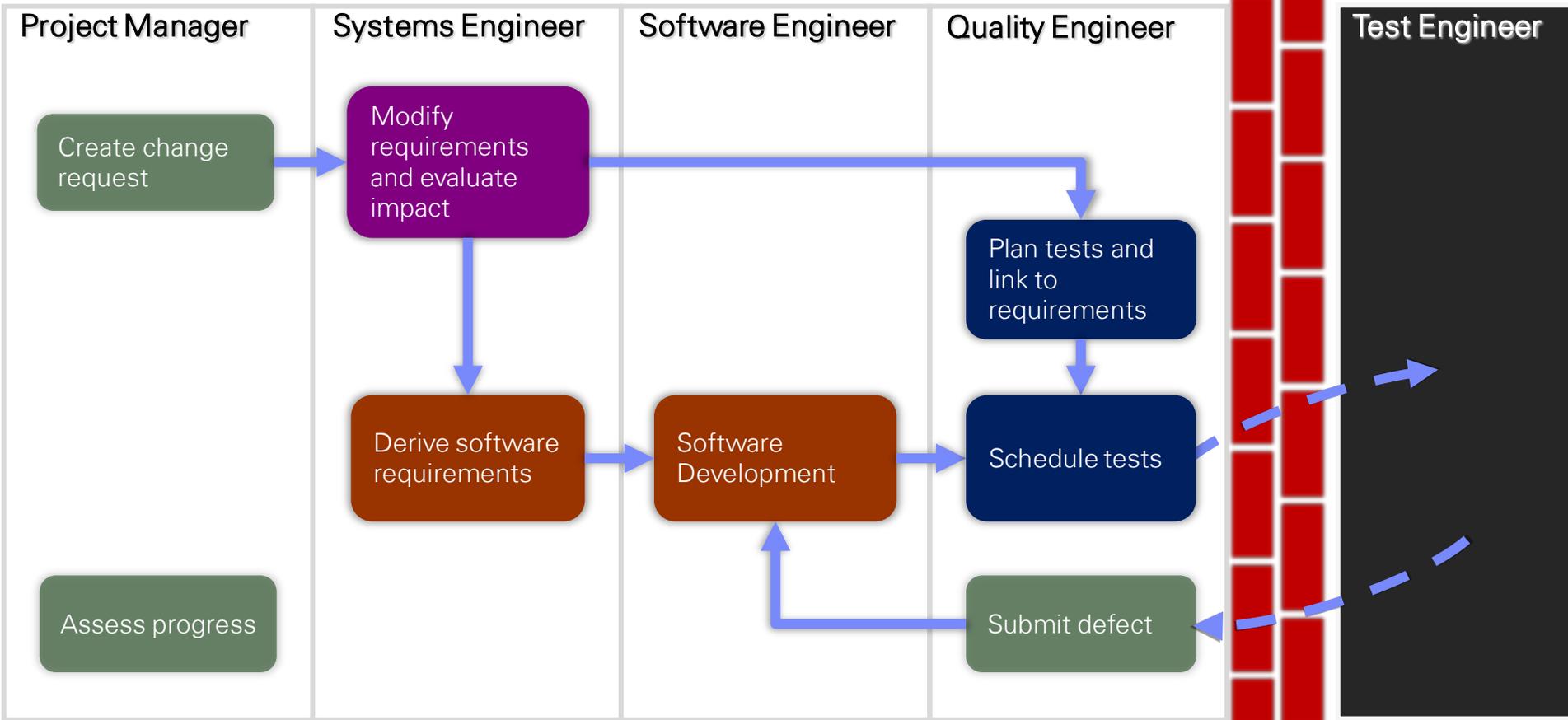
# Diverging Challenges



The **quality challenge** is **growing**, but timelines and budgets are not increasing proportionally

Engineers must continue to **innovate and harness the latest technologies** to remain competitive

# Traditional Development Process



# Quality Engineer

Plan tests and link to requirements



Schedule tests

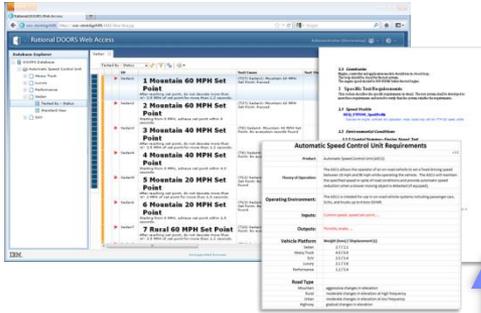
Submit defect



# Test Engineer

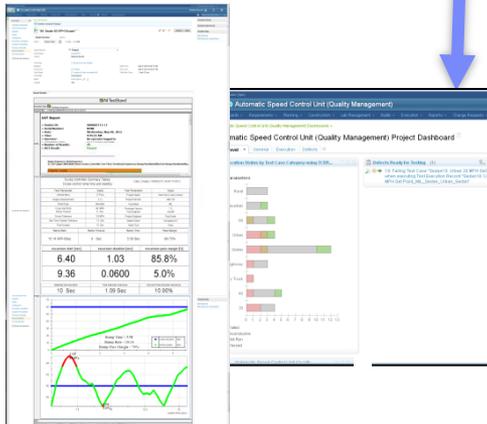
# Requirements Documents

(DOORS, .docx, .xlsx, ...)



## IBM Rational Quality Manager

- Test Plans
- Test Cases
- Test Schedules
- Execution Records
- Requirement Links
- Quality Dashboards



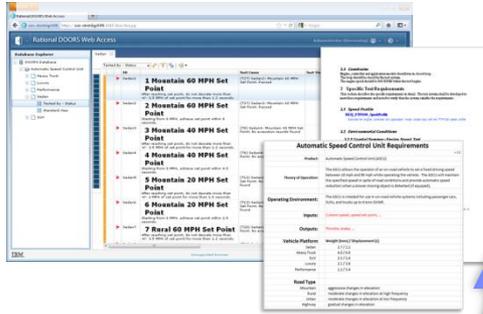
Execution Records, Defect Management, Test Plan Documentation



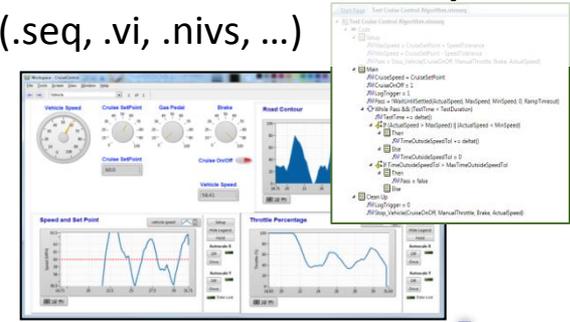
# Test Engineer



# Requirements Documents (DOORS, .docx, .xlsx, ...)



# National Instruments Test Components (.seq, .vi, .nivs, ...)

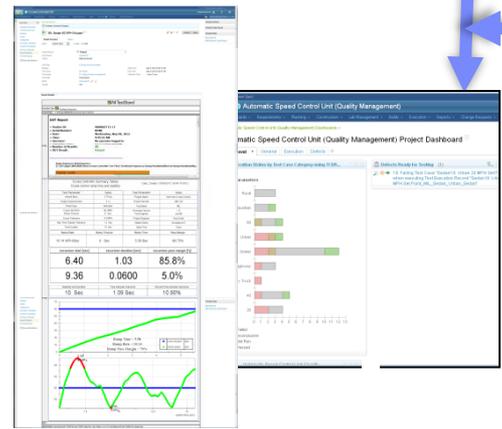


**IBM Rational Quality Manager**

- Test Plans
- Test Cases
- Test Schedules
- Execution Records
- Requirement Links
- Quality Dashboards

**NI TestStand**

- Sequences
- Parameter Files
- Code Modules
- Execution Records
- Requirement Links
- Quality Dashboards

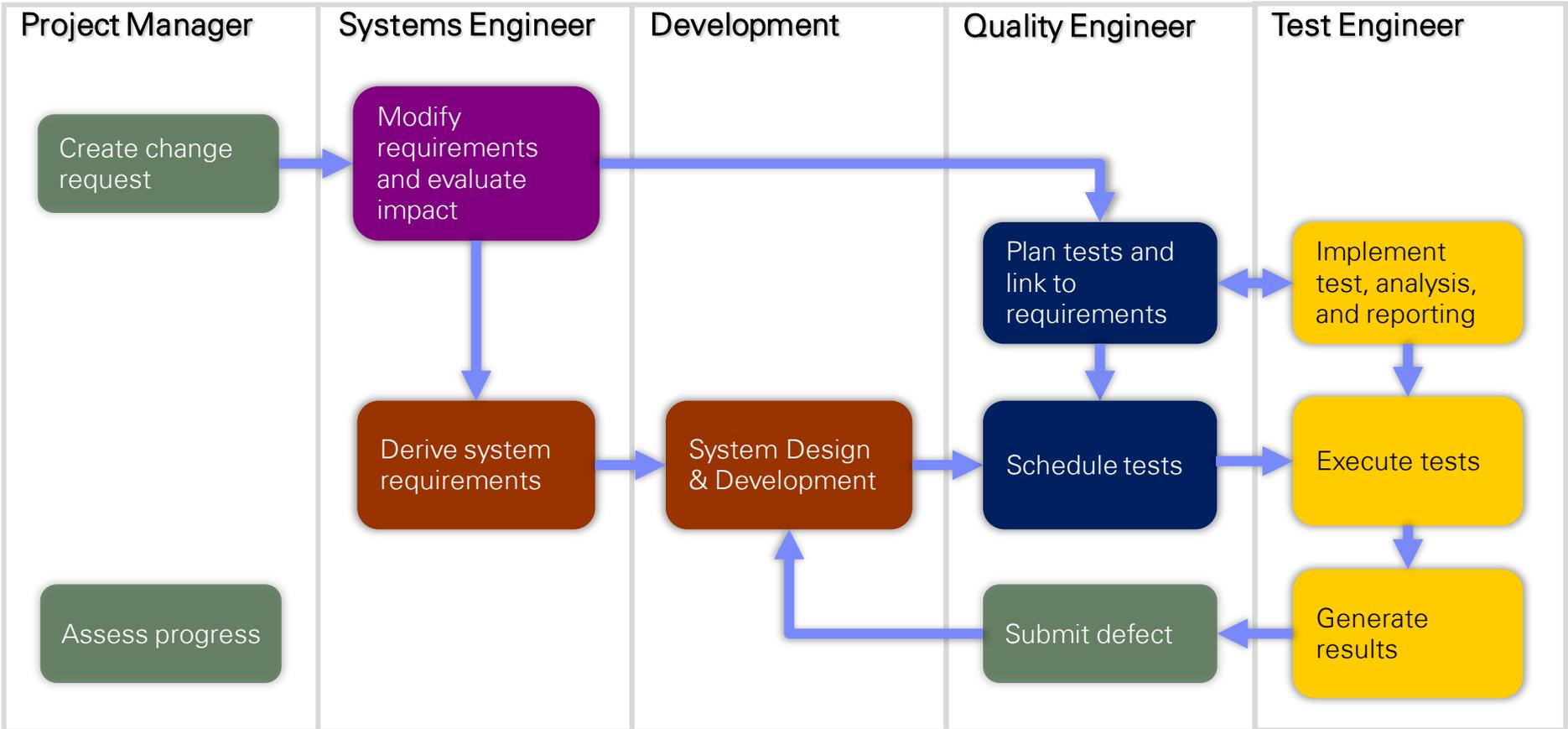


# Test Results (.html, .pdf, .tdms, .jpg, ...)



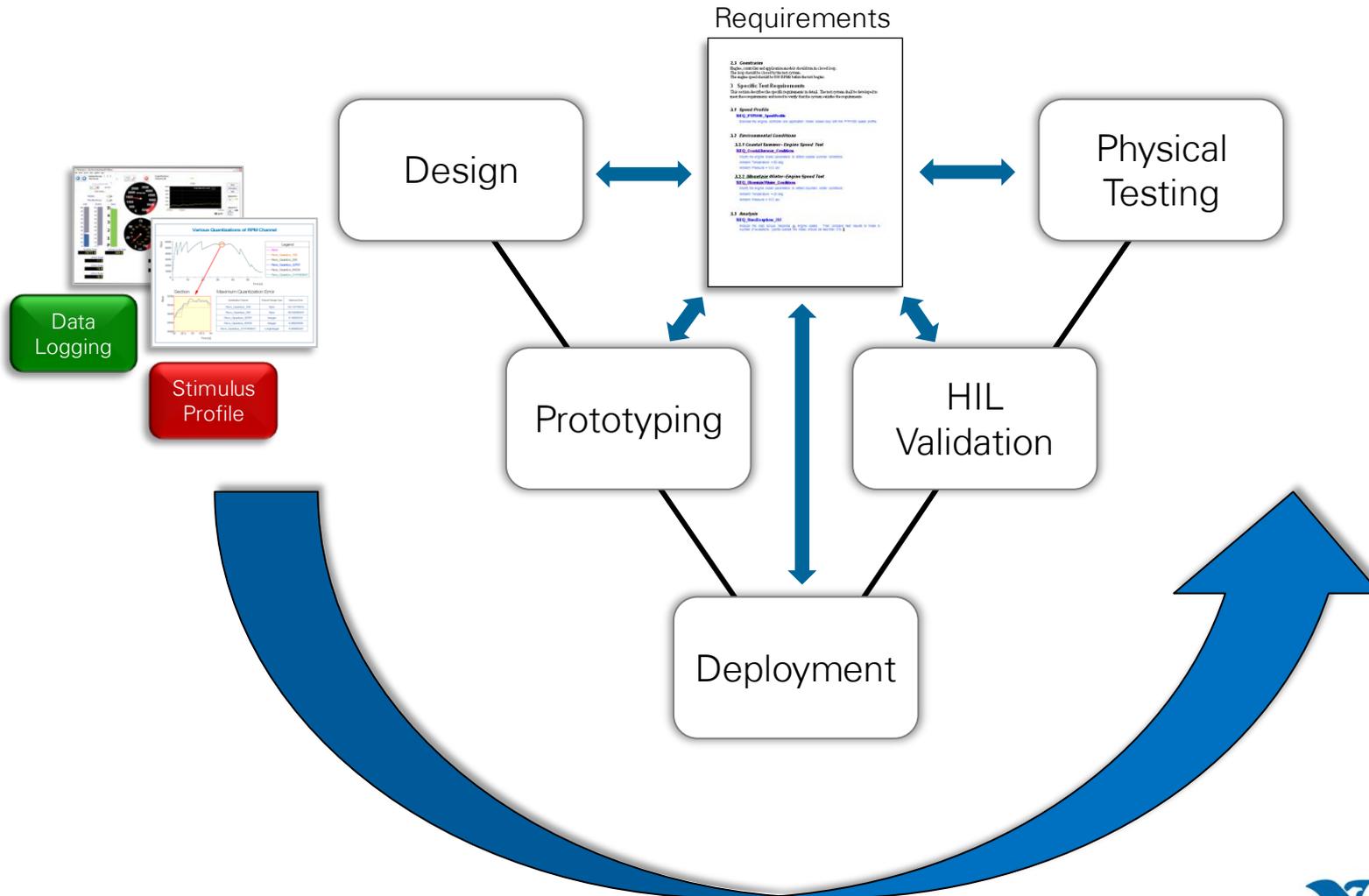
**Execution Records, Defect Management, Test Plan Documentation**

# Next Generation Development Process



DOORS
Rhapsody
Team Concert
Quality Manager
NI TestStand | LabVIEW | NI VeriStand | DIAdem

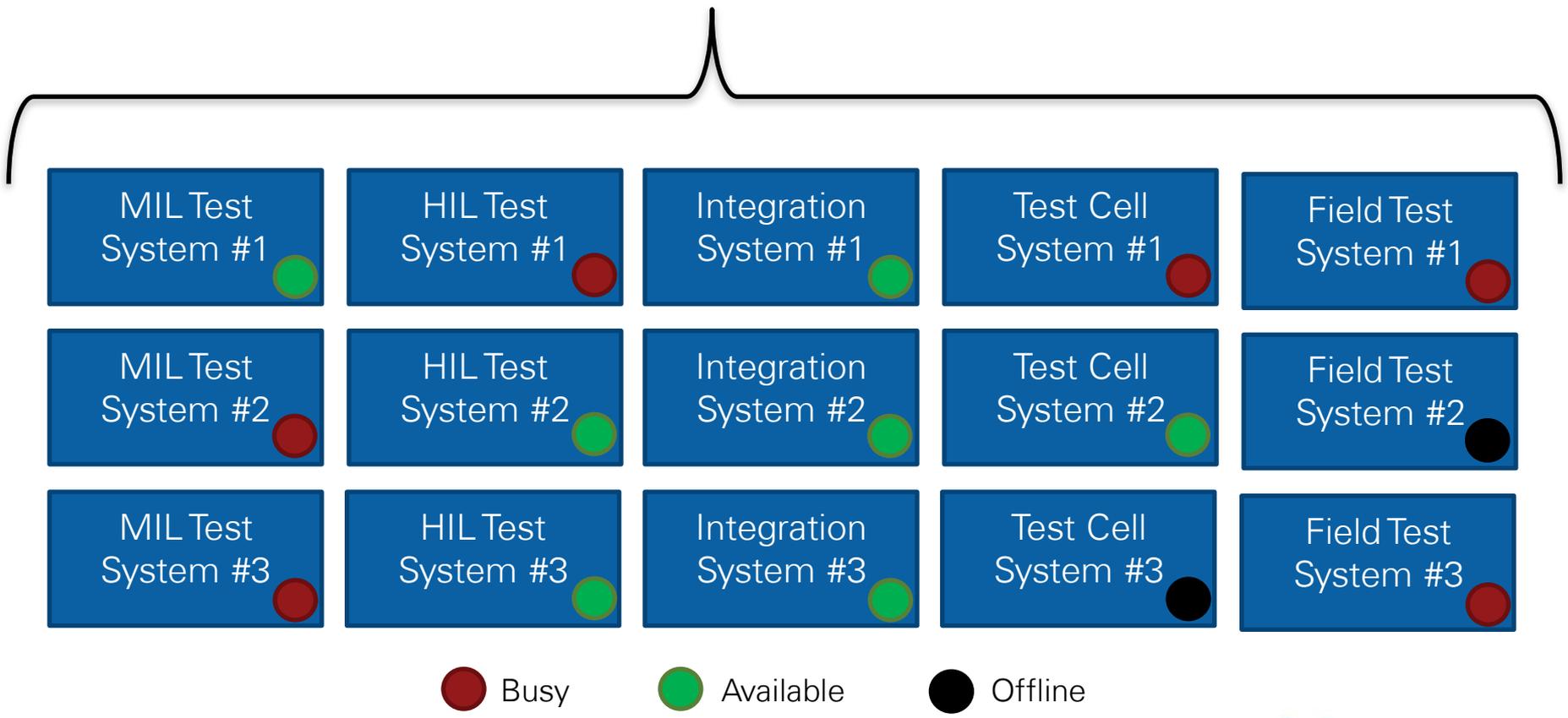
# Consistency and Efficiency throughout the Process



# Test Asset Management and Automation

IBM Rational Quality Manager

- Test Plans
- Test Cases
- Test Schedules
- Execution Records
- Requirement Links
- Quality Dashboards



# Defect Management

## IBM Rational Quality Manager

Test Plans  
Test Cases  
Test Schedules

**Execution Records**  
**Requirement Links**  
Quality Dashboards

Defect Resolution  
Collaboration

Defect Results and  
Verification Items

The screenshot shows the 'Defect 30' page in the IBM Rational Quality Manager. The page title is 'Automatic Speed Control Unit (Change Management)'. The defect is titled 'Failing Test Case "Sedan10 Rural 40 MPH Set Point"'. The 'Overview' tab is active, showing details such as Type: Defect, Filed Against: Automatic Speed Control Unit (Change Management), Severity: Normal, Found In: Unassigned, Project Area: Automatic Speed Control Unit (Change Management), Team Area: Automatic Speed Control Unit (Change Management), Creation Date: Nov 12, 2012 9:32 AM, Created By: Stephen Barrett, and Tags. The description reads 'check the SW calibration -- CPW'. The 'Test Plan' is listed as 'ASCU ML Test'.

The screenshot shows the 'Execution Result - Quality Management' page. The test case is '1801: Sedan10 Rural 40 MPH Set Point'. The result is 'Failed'. The 'Actual Result' is 'NI8PREF2009RE' and the 'Host Name' is 'Stephen Barrett'. The 'Test Plan' is 'ASCU ML Test', 'Test Case' is 'Sedan10 Rural 40 MPH Set Point', and 'Test Script' is 'Sedan 40 MPH Rural ML'. The 'Status' is 'Unassigned' and the 'Weight' is 100. The 'Start Time' is 'Aug 2, 2013 11:52:46 AM' and the 'End Time' is 'Aug 2, 2013 11:53:06 AM'. The 'Total Run Time' is '1 min 11 sec'. The 'TestStand Report' section shows a table of test results:

Test Step	Status	Module Time
Run Cruise Control Test Sequence	Passed	0.9537953
Wait for sequence finish and get result	Failed	0.2367229
Get RQH Progress Percentage	Passed	0.0215592

The report also includes the sequence name 'Begin Sequence: MainSequence' and the file path '(C:\NI\1 Test Scripts\RamoTimeAndStabilityTest\Set RQH Progress.seq)'.

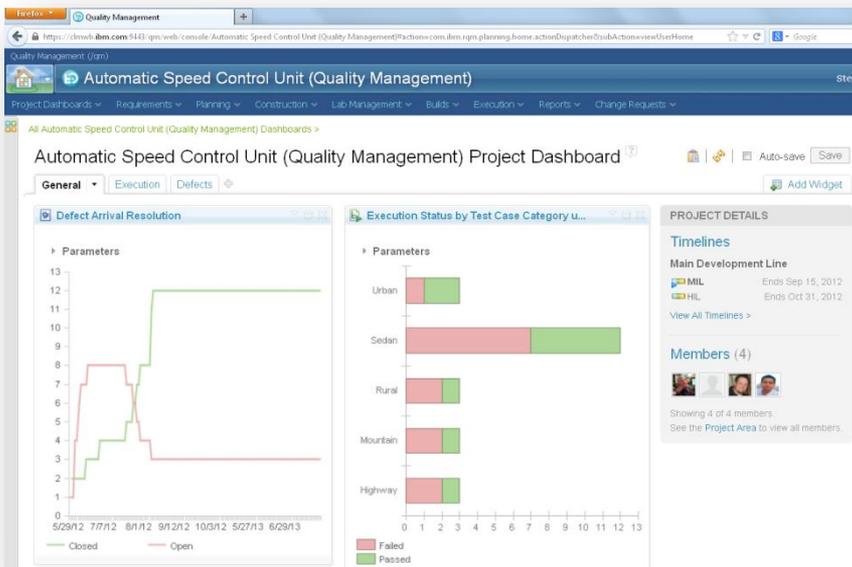
# Project Documentation and Tracking

## IBM Rational Quality Manager

Test Plans      Execution Records  
 Test Cases      Requirement Links  
**Test Schedules**      **Quality Dashboards**

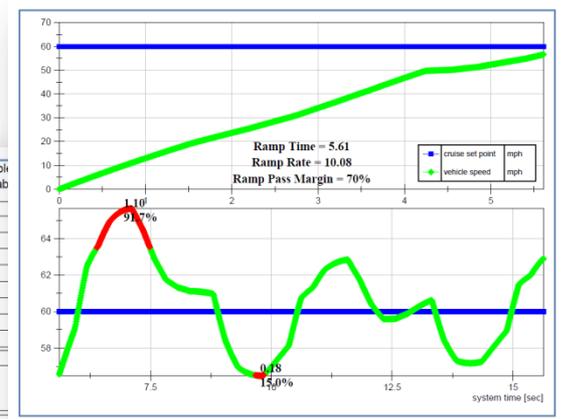
Project  
Dashboards

Test  
Results



Cruise Controller Summary Table  
Cruise control ramp time and stab

Test Parameter	Value
Vehicle Mass	2.7Tons
Engine Displacement	2.1 L
Road Type	Urban
Cruise Set Point	60 MPH
Ramp Timeout	8 Sec
Cruise Tolerance	3.5 MPH
Max Time Outside Tolerance	1.2 Sec
Test Duration	10 Sec



Ramp Rate	Ramp Timeout
10.08 MPH/Sec	8 Sec

excursion start [sec]	excurs...	excurs...
6.39	1.1	91.7%
9.67	0.18	15.0%

Stability Test Duration	Time Outside Tolerance	Percent Time Outside Tolerance
10 Sec	1.28 Sec	12.80%

# Breaking the Quality Management Silos with Enhanced Collaboration and Traceability

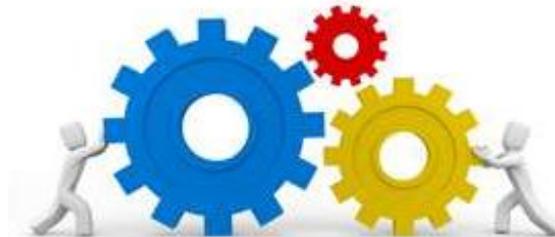
IBM Rational and National Instruments are teaming together to provide an **end-to-end quality management solution**.

**Traceability** all the way to test and back with **Collaboration** between ALL teams, including test

- Test components and assets linked to and managed with quality plan test cases
- All test results available to all teams and linked to test cases and requirements

Promotes quality and test consideration from the outset, not an afterthought, **reducing cost and risk** of identifying and correcting defects

Enables **test component re-use** throughout project phases and between projects providing operational efficiency and accuracy



# Questions?

# Trends in Advanced Powertrain & In-Vehicle RF Communications Research

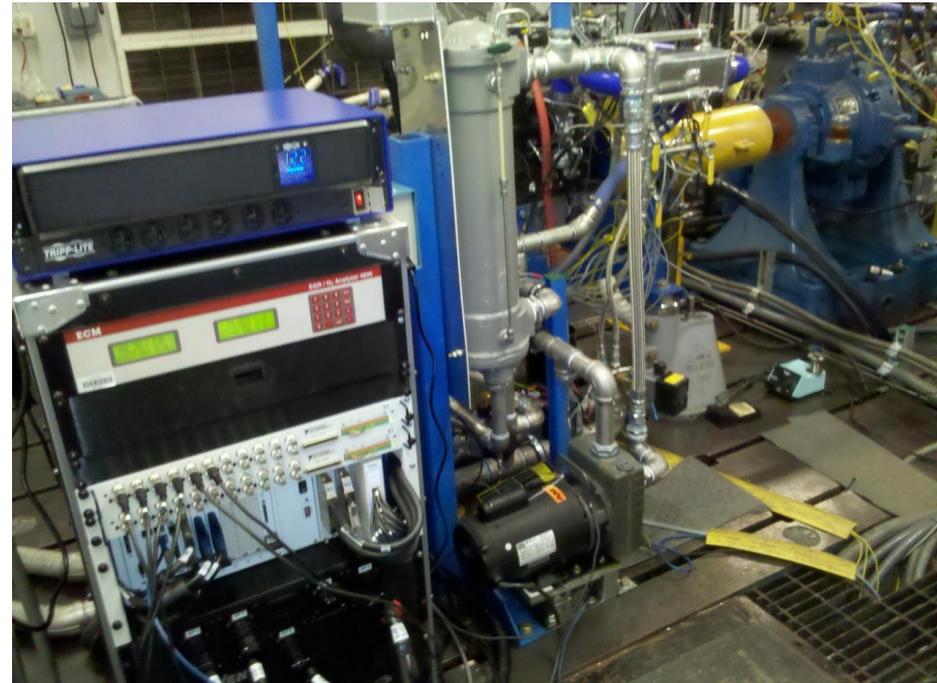
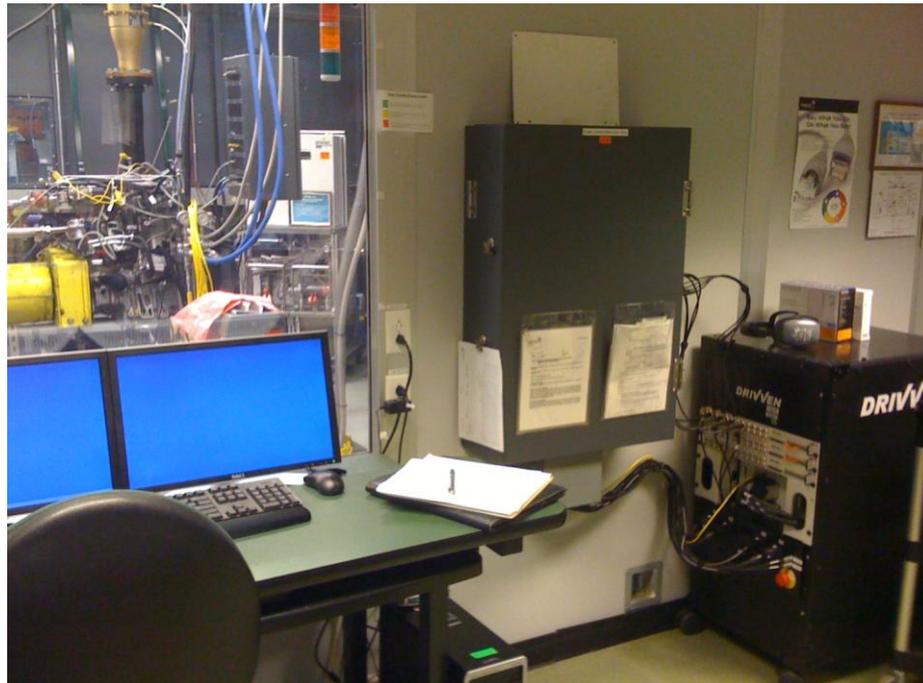
- Fast
- Parallel
- Connect math to real world quickly
- Interactive, integrated systems (complexity)

# Advanced Powertrain Trends

- Fuel efficiency
- Fast control of traditional technologies
  - Fast analysis
  - Fast decision making
  - High speed I/O
- Electrification

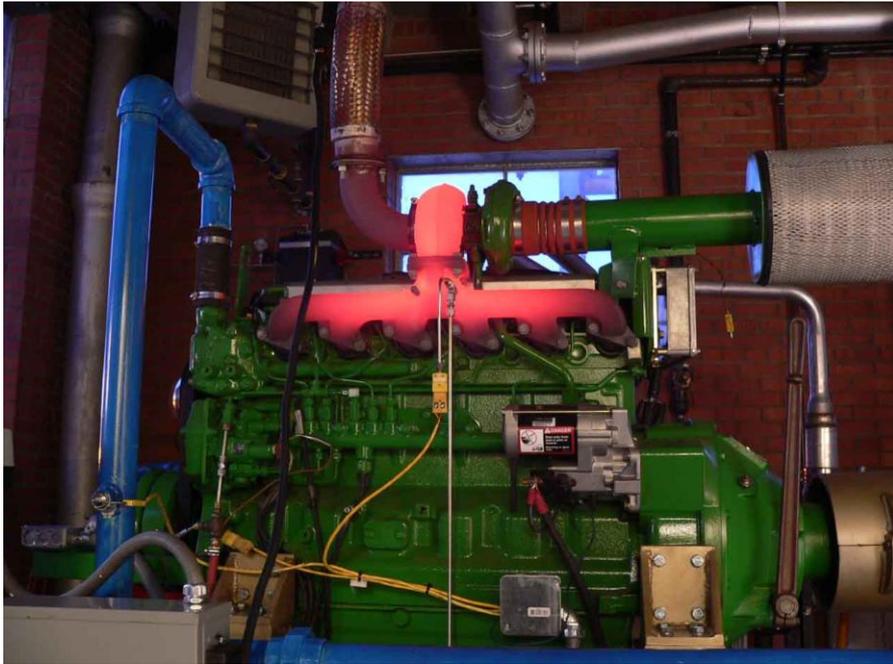
# Oak Ridge and Argonne National Labs

Full authority engine control system with DCAT combustion analysis for same-cycle and next-cycle control



# University Research

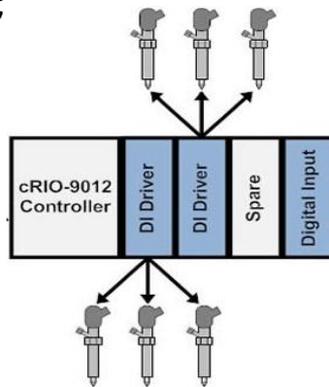
Diesel, gasoline, natural gas, and alternative fuel research systems in 19 universities around the world



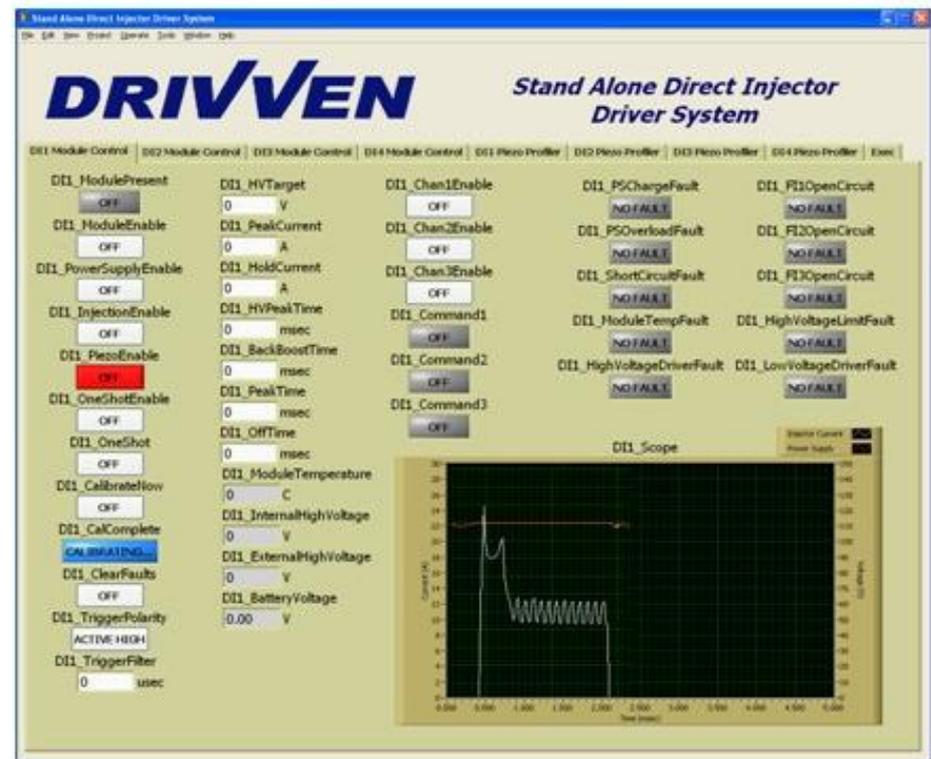
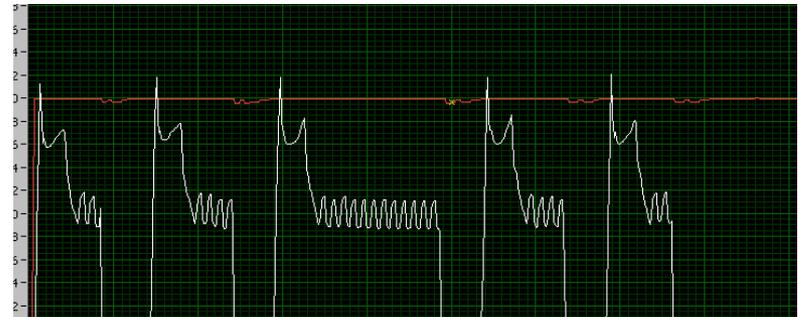
# Injector Driver Kits

## Direct Injector Drive Kit

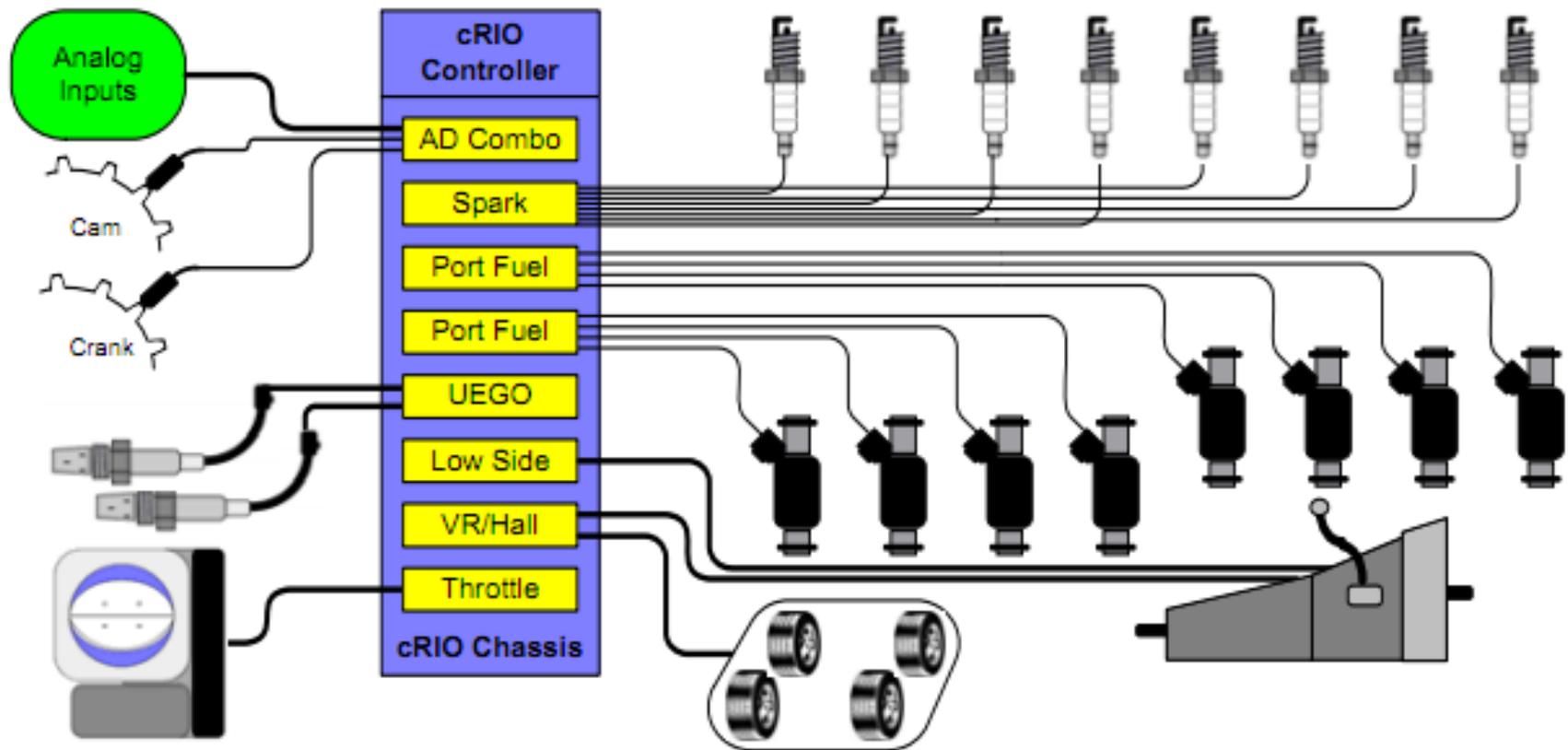
- Driver stage to interface with existing controller commands
- Ready to run out-of-box at power-up
- Calibration interface over Ethernet
- Add custom I/O for rail pressure control, etc



Stand-Alone Kits



# Typical Engine Control Application



# System Diagram

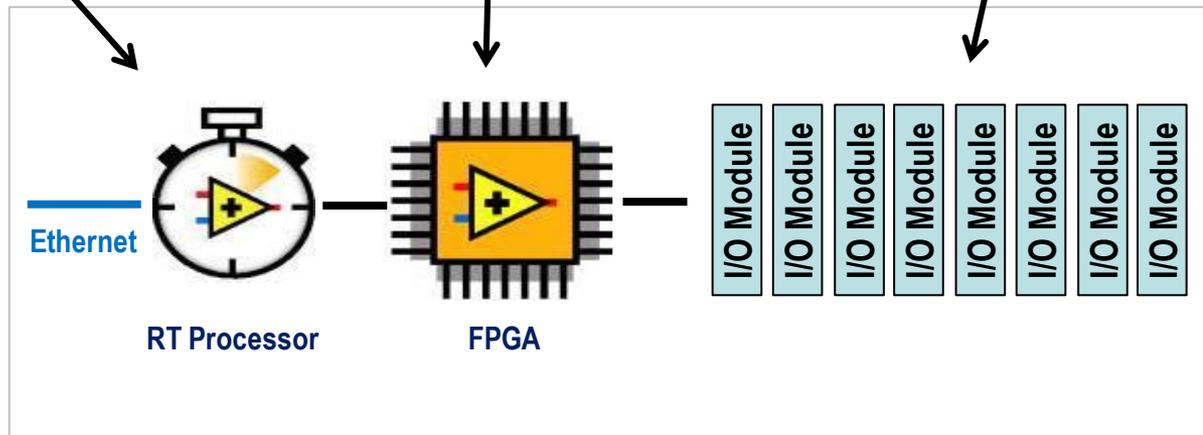


Engine control software and calibration points

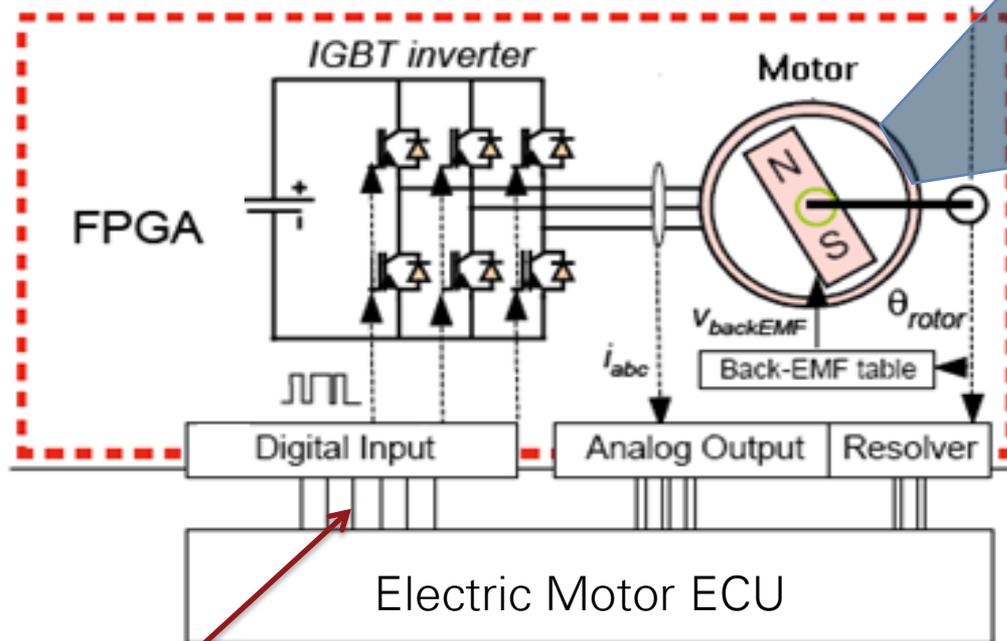
FPGA-based "driver" code for modules (ie EPT)

User-defined I/O configuration

User Interface Link: →



# Electric Motor Systems



25kHz PWM

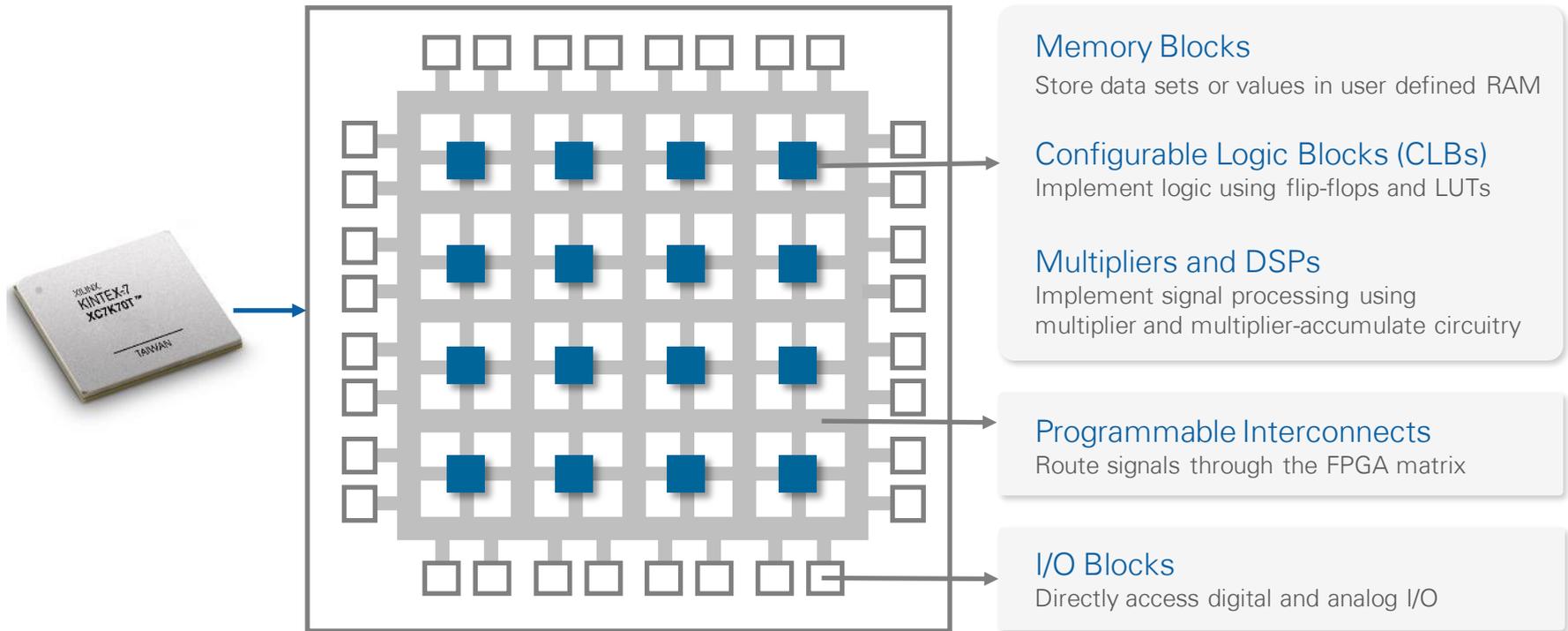
Simulated plant model needs to execute >10x the rate of the control system

# Operating System Characteristics

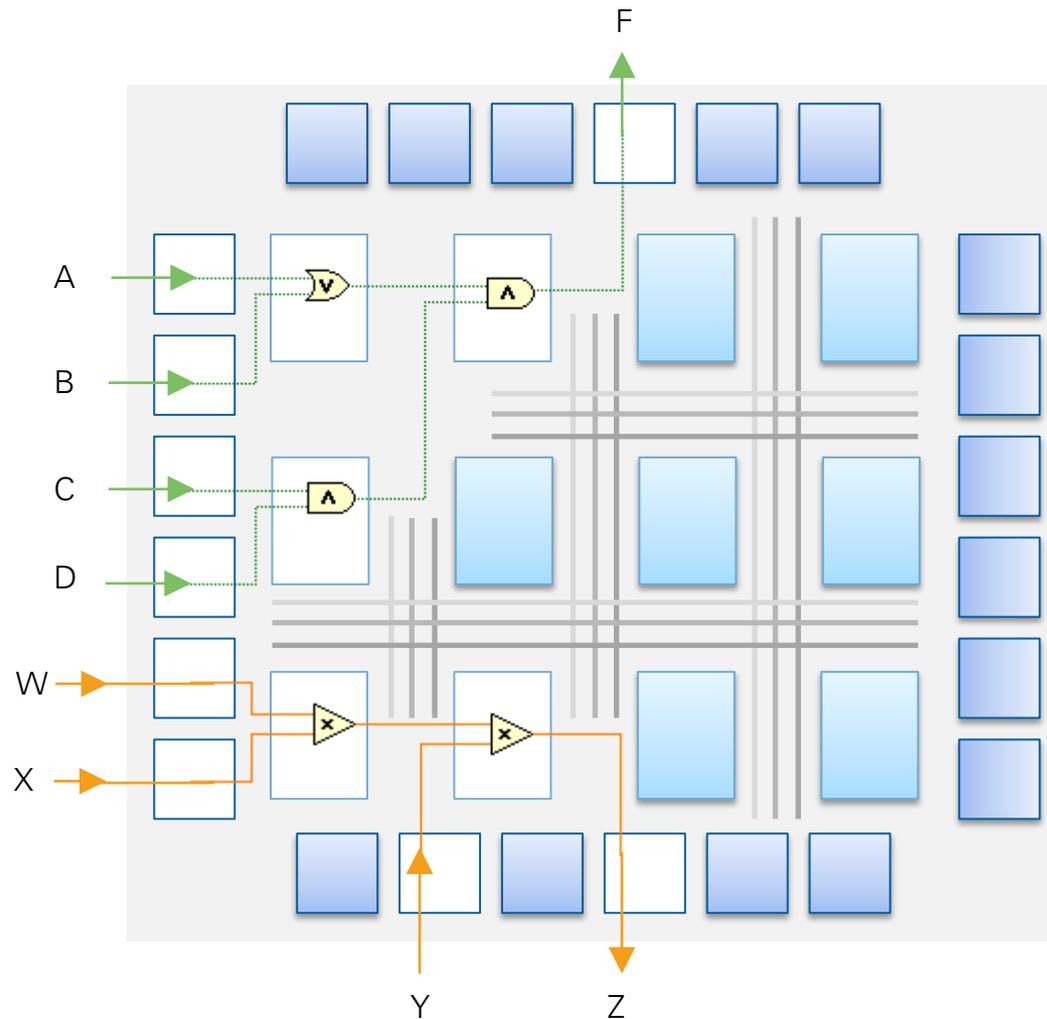
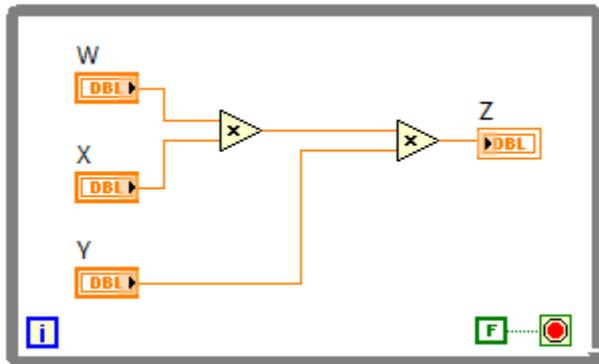
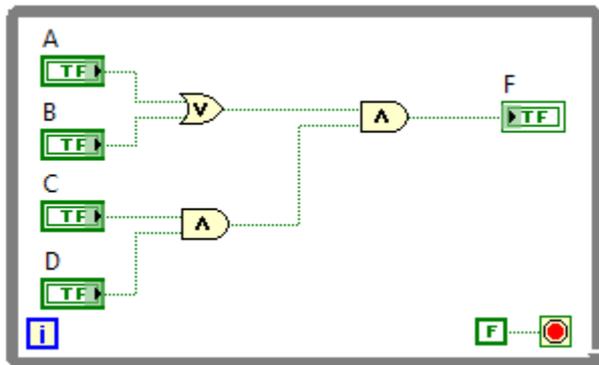
	<i>Loop Rate</i>	<i>Jitter</i>
<b>General Purpose OS</b> <ul style="list-style-type: none"><li>• High-priority tasks can be preempted by lower-priority tasks</li><li>• Extraneous background programs<ul style="list-style-type: none"><li>- Screen savers, disk utilities, virus software, and so on</li></ul></li><li>• Peripheral Interrupts<ul style="list-style-type: none"><li>- Mouse, keyboard, and so on</li></ul></li></ul>	<i>10-100 Hz</i>	<i>Unbounded</i>
<b>Real-Time OS</b> <ul style="list-style-type: none"><li>• Scheduler ensures high-priority tasks execute first</li><li>• Direct control over all tasks</li><li>• Stand-alone<ul style="list-style-type: none"><li>• no mouse, keyboard, and so on</li></ul></li></ul>	<i>Up to 50 kHz</i>	<i>Bounded</i>

# Software Designed Hardware

## Field-Programmable Gate Array (FPGA)

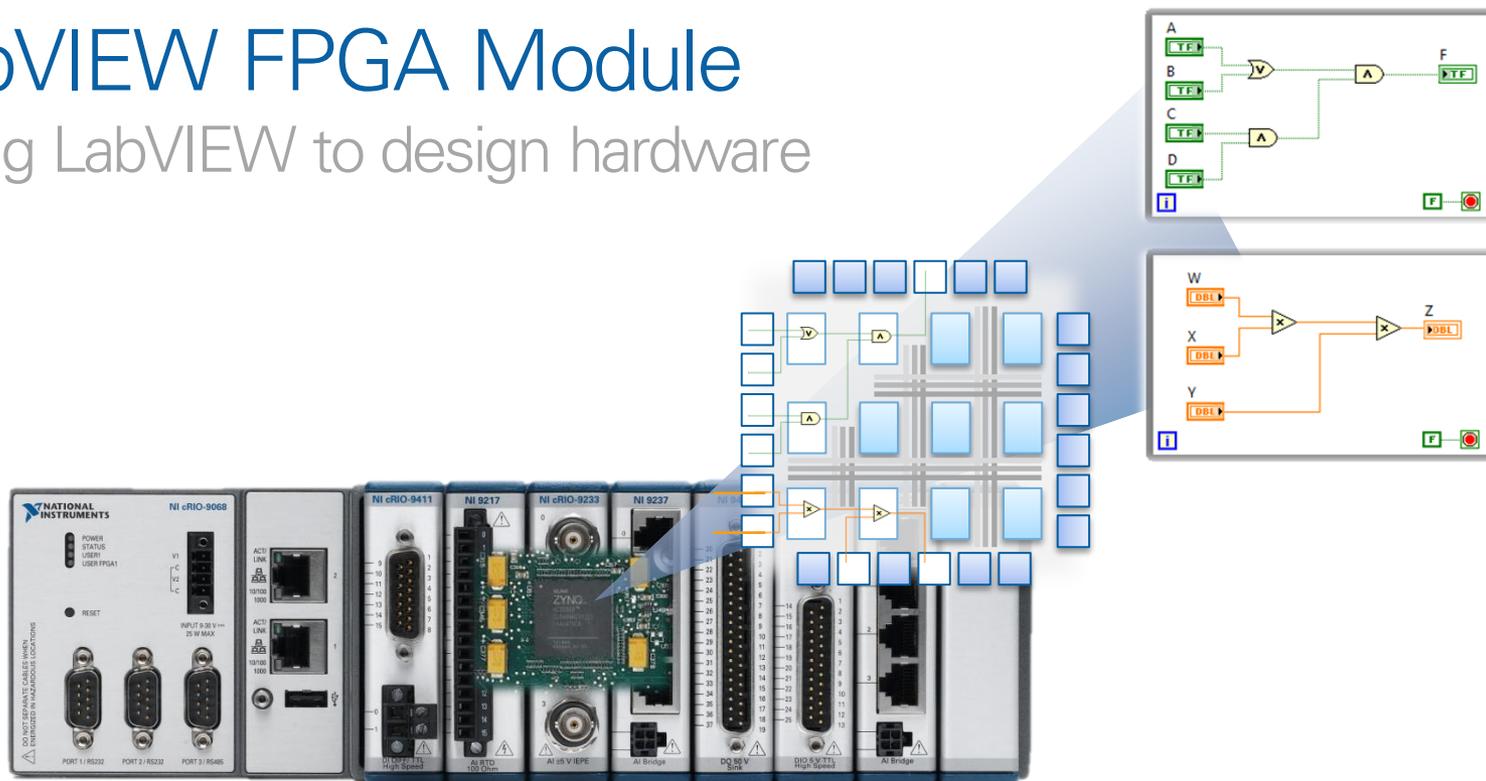


# FPGA: Parallel Processing



# LabVIEW FPGA Module

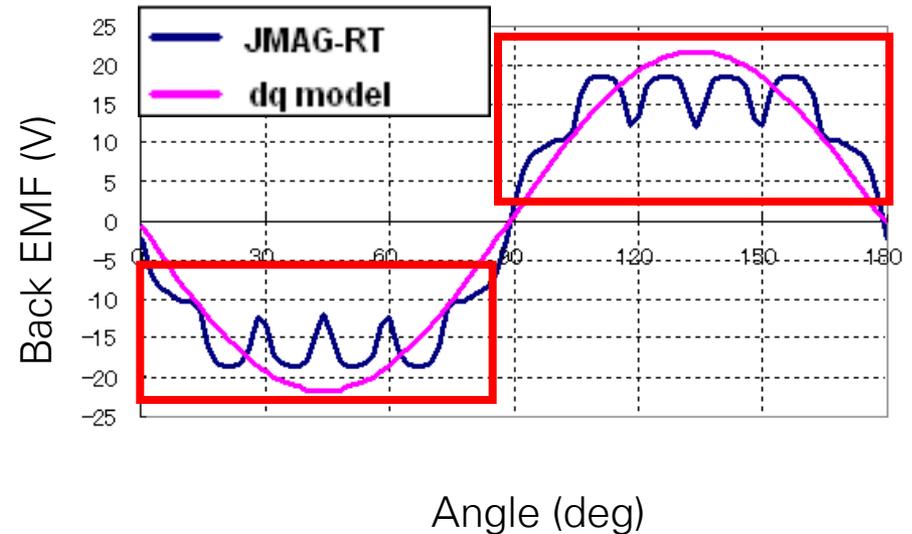
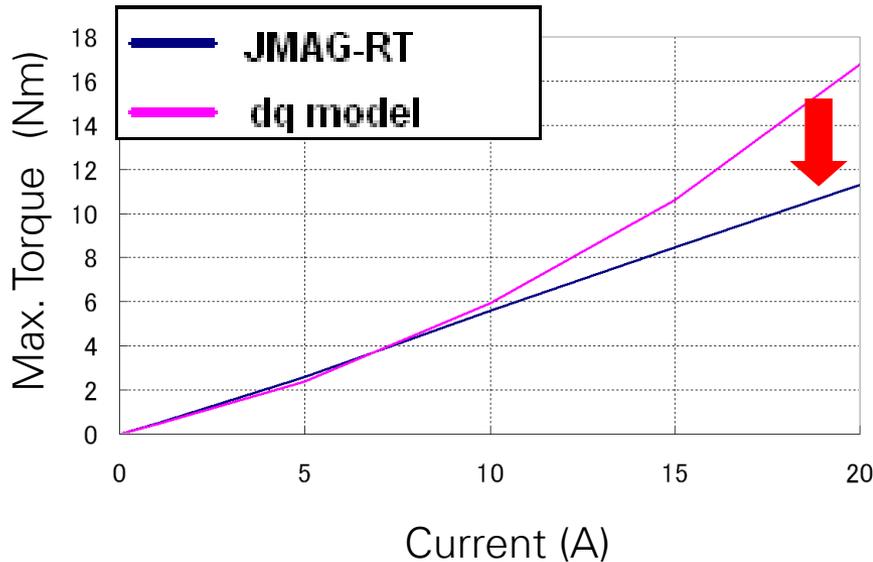
Using LabVIEW to design hardware



Replace custom circuitry with software-programmable FPGA logic

- High speed control: 1 MHz digital / counter-timer, 200 kHz motion control / analog PID
- Dedicated logic in silicon for highest reliability
- Custom timing, triggering, synchronization, counter/timers, PWM
- Pre-process data in parallel prior to execution on the CPU for high-throughput applications

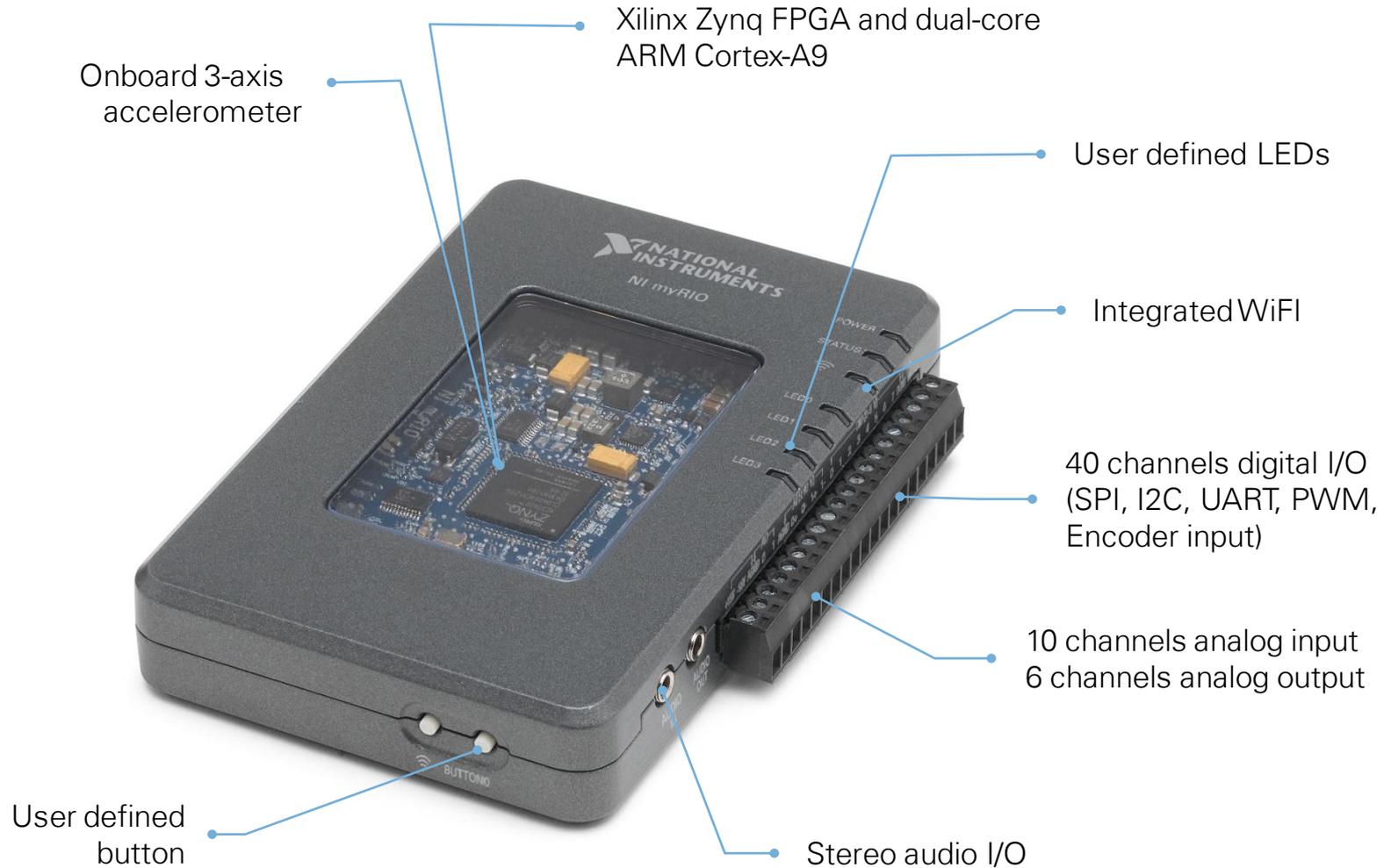
# Difference between DQ model and JMAG-RT model



- Saturation effects are critical for the current control.
- Geometry effects are critical for the back EMF tracking.
- JMAG-RT models are accurate enough for the control design.

<b>Model</b>	<b>Execution Target</b>	<b>Simulation Fidelity</b>	<b>Real-Time Simulation Speed</b>
FEA with JMAG	Windows	High	Non-RT: Minutes to hours
DQ Model with JMAG-RT	Windows Real-Time	Medium	20-30 us
	NI FPGA	Medium	2-3 us
JMAG –RT FEA Model	Windows Real-Time	Medium	20-30 us
	NI FPGA Hardware	High	~1-2 us

# NI myRIO

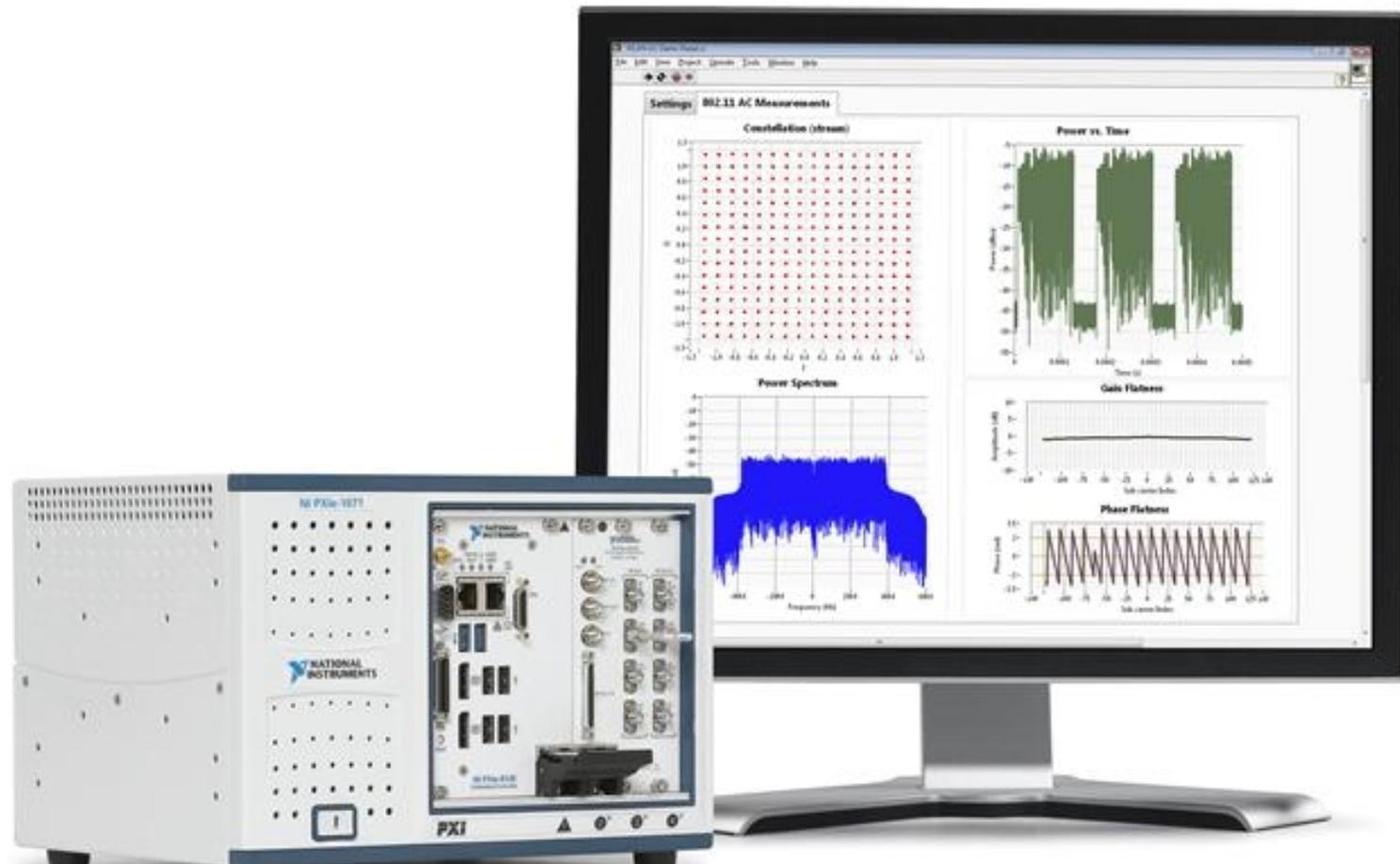


# Additional Features



- Fully programmable FPGA through LabVIEW FPGA
- Dual-Core ARM Cortex-A9 processor
- Expandable ecosystem of sensors and actuators
- Ready to use projects and courseware
- Deploy code to real-time processor and FPGA via USB or WiFi
- Minutes to first measurement
- Processor programmable in C/C++

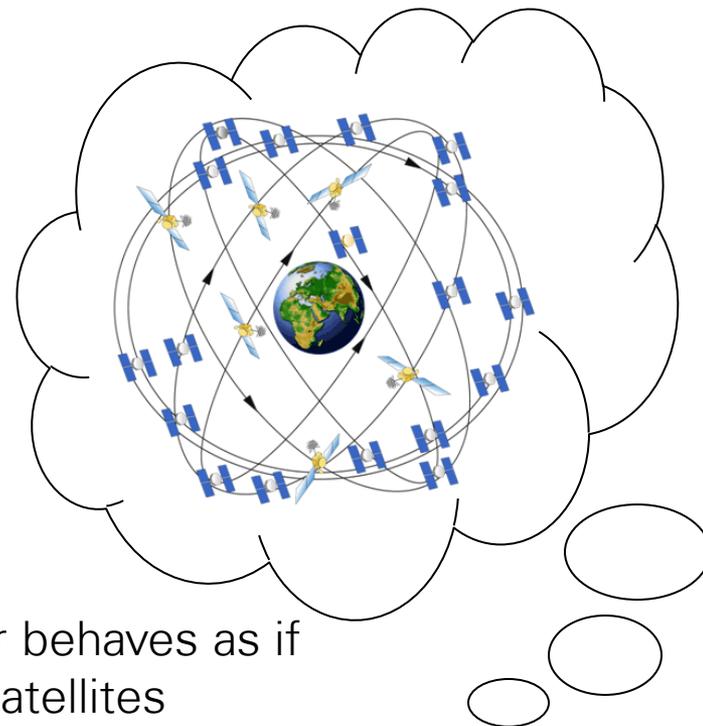
# NI PXI-based System for RF Simulation & Test



# GPS Simulation Works

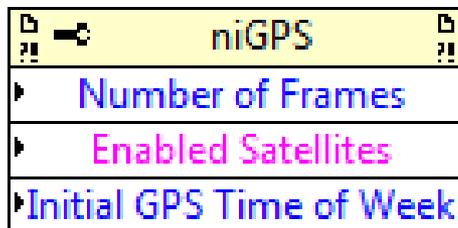
## Things to Simulate

- Poor signal strength
- View of satellites obstructed
- Position constantly changing



GPS receiver behaves as if it sees real satellites

GPS toolkit Creates Signal in LabVIEW



PXIe-5673 VSG Generates Signal

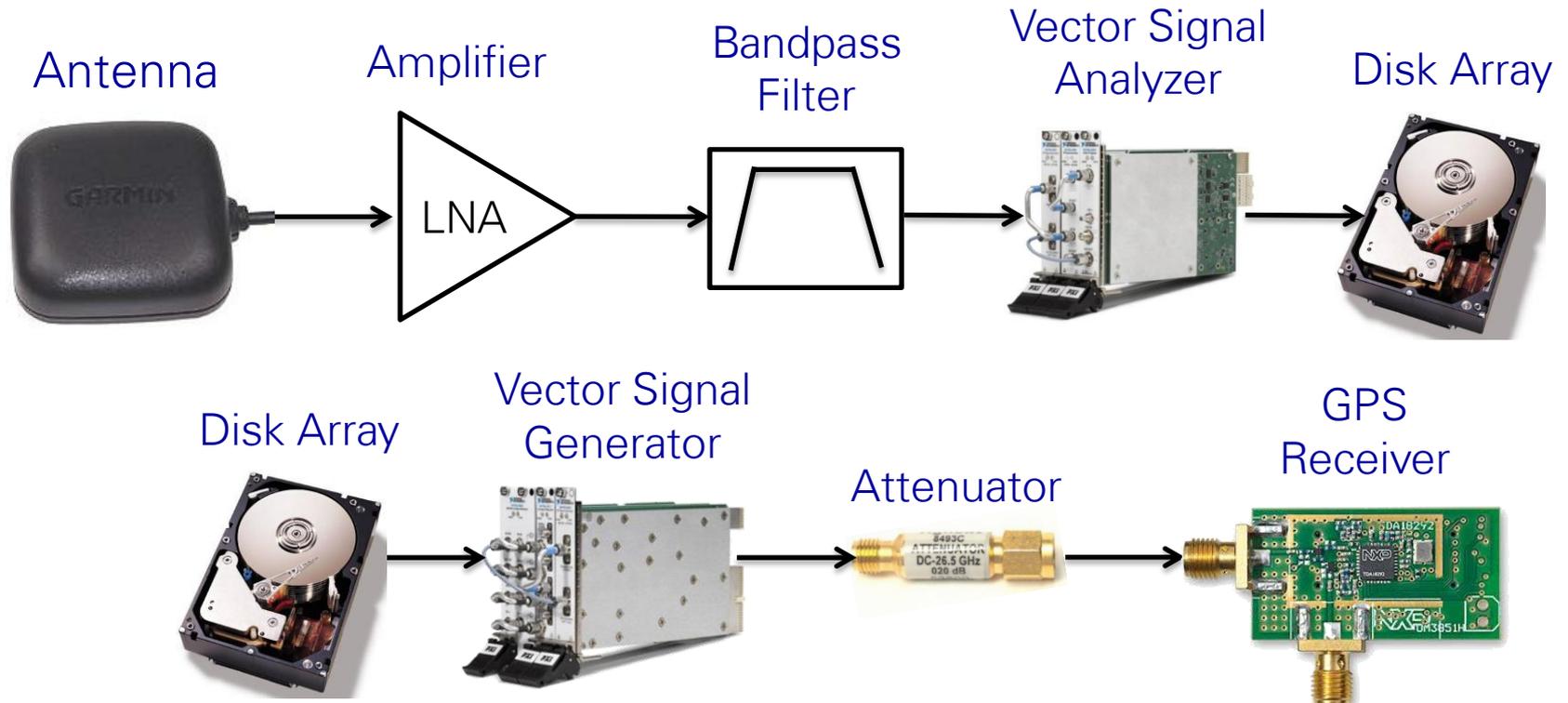


GPS Receiver



# RF Record and Playback for GPS

- RF record and playback produces a repeatable field test
- Signal can be played back from disk with a vector signal generator
  - 2 TB raid drive can playback 25 hours of GPS signal



# Think Platform.

## Simplify

Integrated software and hardware that simplifies system integration of processing, I/O, and data

## Customize

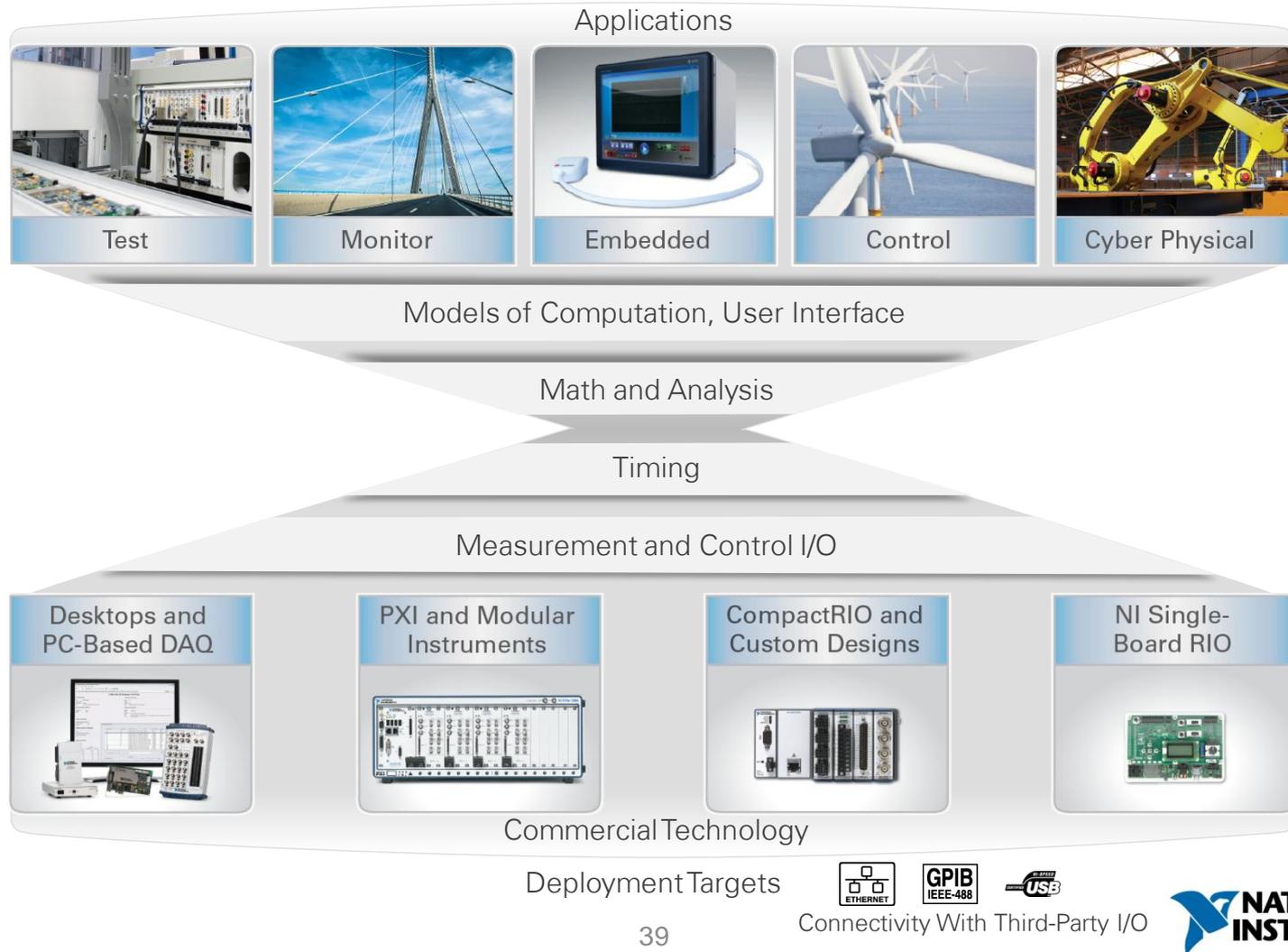
Flexible, modular platform that scales to changing needs and integrates commercial technology

## Reuse

Supported by a community of users, partners, products, and examples

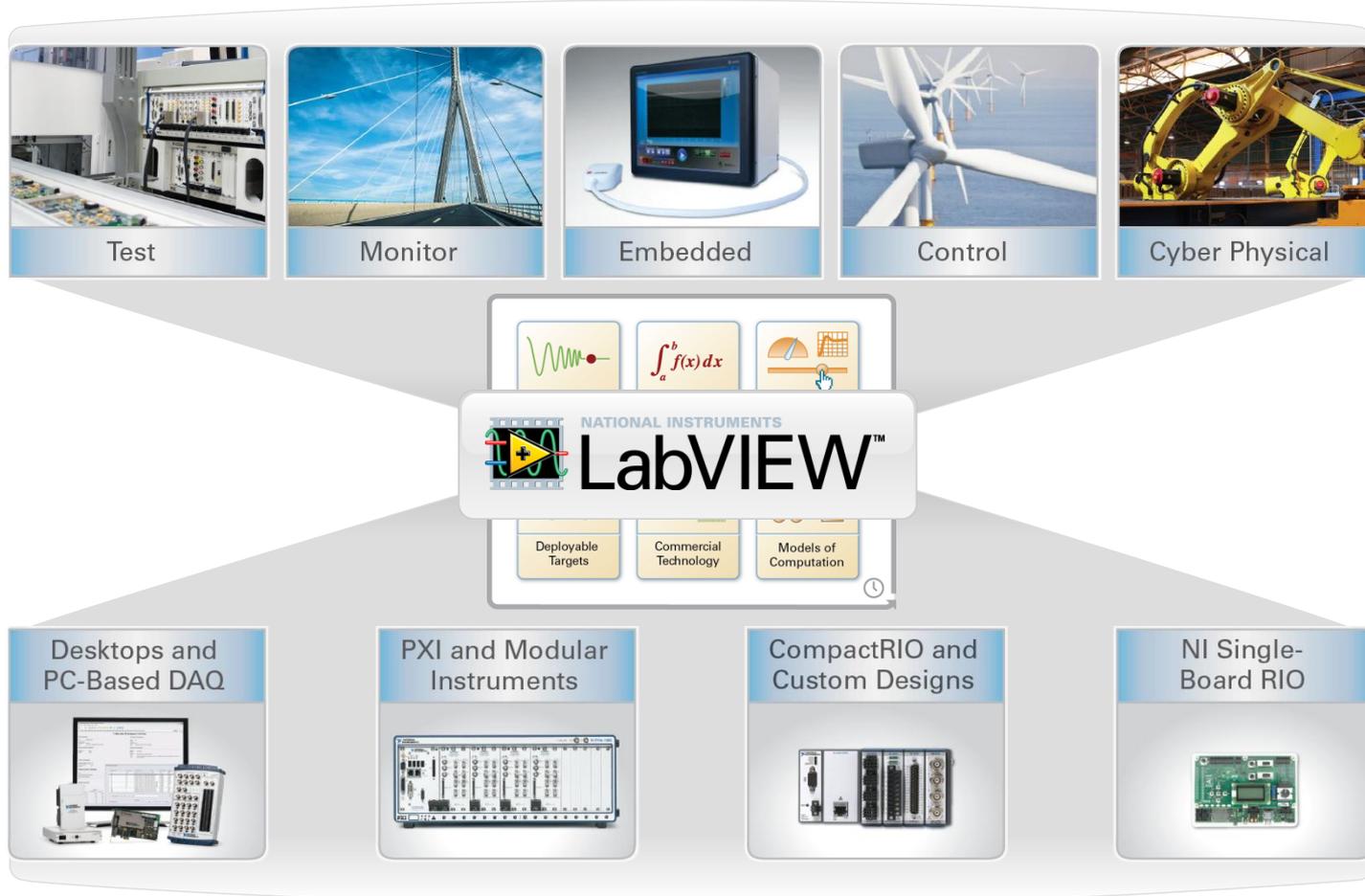
# Graphical System Design

A platform-based approach for measurement and control



# Graphical System Design

A platform-based approach for measurement and control





# NI VeriStand™

## Real-Time Testing and Simulation Software

- RT Stimulus Generation
- Data Logging
- Test Automation
- Single-Point I/O
- Alarming
- Calculated Channels
- Deterministic Model Execution
- User Account Management
- Multi-Chassis Synchronization
- Multi-Chassis Data Sharing
- Closed-Loop Control
- Scaling and Calibration



**Multi-Chassis Systems**



**PXI**



**CompactRIO\***



**Single-Board RIO\***

*\* 128MB DRAM or great required*

# Multimedia Testing and Simulation



 **NI VeriStand™**



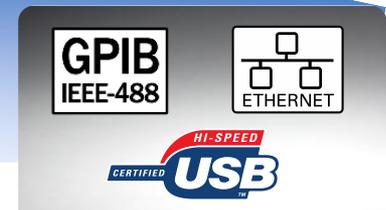
Desktops and  
PC-Based DAQ



PXI and Modular  
Instruments



RIO and Custom  
Designs



Open Connectivity  
with 3<sup>rd</sup> Party I/O